Trimble R12i

GNSS SYSTEM

KEY FEATURES

- Trimble[®] Inertial Platform[™] (TIP) technology. Calibration-free and magnetically immune IMU-based tilt compensation for topo measurements and stakeout.
- ► Trimble ProPoint™ GNSS positioning engine. Engineered for improved accuracy and productivity in challenging GNSS conditions.
- ► 672-channel solution with Trimble 360 satellite tracking technology
- ► CenterPoint® RTX correction service delivers fast, RTK level accuracy worldwide via satellite/IP
- ► Trimble xFill® correction outage technology
- Doptimized for Trimble Access™ field software
- ► Android[™] and iOS platform support
- Cellular, Bluetooth®, Wi-Fi data connectivity
- Military-spec rugged design and IP-67 rating
- Ergonomic form factor
- All day battery with built-in status indicator
- ► 6 GB internal memory
- Supports augmented reality capabilities through Trimble SiteVision™

Learn more: geospatial.trimble.com/R12i







PERFORMANCE SPECIFICATION	NS		
GNSS MEASUREMENTS			
	Constellation agnostic, flexible signal tracking, improved positioning in challenging environments¹ and inertial measurement integration with Trimble ProPoint GNSS technology. Increased measurement and stakeout productivity and traceability with Trimble TIP™ technology IMU-based till compensation.		
	Advanced Trimble Custom Survey GNSS chips with 672 channels		
	Reduced downtime due to loss of radio signal or cellular co		
	Signals tracked simultaneously	GPS: L1C, L1C/A, L2C, L2E, L5 GLONASS: L1C/A, L1P, L2C/A, L2P, L3 SBAS (WAAS, EGNOS, GAGAN, MSAS): L1C/A, L5 Galileo: E1, E5A, E5B, E5 AltBOC, E6² BeiDou: B1, B1C, B2, B2A, B2B, B3 QZSS: L1C/A, L1S, L1C, L2C, L5, L6 NavIC (IRNSS): L5 L-band: Trimble RTX™ Corrections	
	Iridium filtering above 1616 MHz allows antenna to be used		
	Japanese LTE filtering below 1510 MHz allows antenna to b	·	
	Digital Signal Processor (DSP) techniques to detect and rec	-	
	Advanced Receiver Autonomous Integrity Monitoring (RAII to improve position quality Improved protection from erroneous ephemeris data	VI) algorithm to detect and reject problem satellite measurements	
	Positioning Rates	1 Hz, 2 Hz, 5 Hz, 10 Hz, and 20 Hz	
DOCITIONING DEDECTMANCES		2 - 12 - 12 - 12 - 12 - 12 - 12 - 12 -	
POSITIONING PERFORMANCE ³			
STATIC GNSS SURVEYING			
High-Precision Static	Horizontal	3 mm + 0.1 ppm RMS	
	Vertical	3.5 mm + 0.4 ppm RMS	
0	vertical	3.5 mm + 0.4 ppm kms	
Static and Fast Static	11	2 + 0.F DMC	
	Horizontal	3 mm + 0.5 ppm RMS	
	Vertical	5 mm + 0.5 ppm RMS	
REAL TIME KINEMATIC SURVEYING			
Single Baseline <30 km			
	Horizontal	8 mm +1 ppm RMS	
	Vertical	15 mm + 1 ppm RMS	
Network RTK ⁴			
	Horizontal	8 mm + 0.5 ppm RMS	
	Vertical	15 mm + 0.5 ppm RMS	
RTK start-up time for specified precisions ⁵		2 to 8 seconds	
TRIMBLE INERTIAL PLATFORM (TIP)	TECHNOLOGY		
TIP Compensated Surveying ⁶			
···· componented carroying	Horizontal	RTK + 5 mm + 0.4 mm/° tilt (up to 30°) RMS	
	Horizontal	RTX + 5 mm + 0.4 mm/° tilt (up to 30°) RMS	
IMU Integrity Monitor	Bias monitoring	Temperature, age and shock	
TRIMBLE RTX CORRECTION SERVICE	ŭ .		
CenterPoint RTX ⁷	LO		
Center Official A	Horizontal	2 cm RMS	
	Vertical	5 cm RMS	
	RTX convergence time for specified precisions in Trimble	<1min	
	RTX Fast regions RTX convergence time for specified precisions in non RTX Fast regions	< 15 min	
	RTX QuickStart convergence time for specified precisions	<1min	
TRIMBLE xFILL8			
	Horizontal	RTK ⁹ + 10 mm/minute RMS	
	Vertical	RTK ⁹ + 20 mm/minute RMS	
TRIMBLE xFILL PREMIUM8			
The state of the s	Horizontal	3 cm RMS	
	Vertical	7 cm RMS	
CODE DIFFERENTIAL GNSS POSITIO			
OODE DITTERENTIAL GINSST OSITIO	Horizontal	0.25 m + 1 ppm RMS	
	Vertical	0.50 m + 1 ppm RMS	
	SBAS ¹⁰	typically <5 m 3DRMS	
	05/10	Cypically Componition	

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HARDWARE			
PHYSICAL			
Dimensions (W×H)	11.9 cm x 13.6 cm (4.6 in x 5.4 in)		
Weight	1.12 kg (2.49 lb) with internal battery, internal radio with UHF antenna, 3.95 kg (8.71 lb) items above plus range pole, Trimble TSC7 controller & bracket		
Temperature ¹¹			
	Operating	-40 °C to +65 °C (-40 °F to +149 °F)	
	Storage	-40 °C to +75 °C (-40 °F to +167 °F)	
Humidity		100%, condensing	
Ingress protection		IP67 dustproof, protected from temporary immersion to depth of 1m (3.28 ft)	
Shock and vibration (Tested and meets the	e following environmental standards)		
	Shock	Non-operating: Designed to survive a 2 m (6.6 ft) pole drop onto concrete. Operating: to 40 G, 10 msec, sawtooth	
	Vibration	MIL-STD-810F, FIG.514.5C-1	
ELECTRICAL			
	Power 11 to 24 V DC external power input with over-voltage protection on Port 1 and Port 2 (7-pin Lemo)		
	Rechargeable, removable 7.4 V, 3.7 Ah Lithium-ion smart battery with LED status indicators		
	Power consumption is 4.2 W in RTK rover mode with internal radio ¹²		
Operating times on internal battery ¹³			
	450 MHz receive only option	6.5 hours	
	450 MHz receive/transmit option (0.5 W)	6.0 hours	
	450 MHz receive/transmit option (2.0 W)	5.5 hours	
	Cellular receive option	6.5 hours	
COMMUNICATIONS AND DATA	STORAGE		
Serial	3-wire serial (7-pin Lemo)		
USB v2.0	Supports data download and high speed communication	Supports data download and high speed communications	
Radio modem	Fully Integrated, sealed 450 MHz wide band receiver/transmitter with frequency range of 403 MHz to 473 MHz, support of Trimble, Pacific Crest, and SATEL radio protocols:		
	Transmit power	2 W	
	Range	3–5 km typical / 10 km optimal ¹⁴	
Cellular ¹⁵	Integrated, 3.5 G modem, HSDPA 7.2 Mbps (download), GPRS multi-slot class 12, EDGE multi-slot class 12, Penta-band UMTS/HSDPA (WCDMA/FDD) 800/850/900/1900/2100 MHz, Quad-band EGSM 850/900/1800/1900 MHz, GSM CSD, 3GPP LTE		
Bluetooth	Fully integrated, fully sealed 2.4 GHz communication	Fully integrated, fully sealed 2.4 GHz communications port (Bluetooth) ¹⁶	
Wi-Fi	802.11 b,g, access point and client mode, WPA/WPA	2/WEP64/WEP128 encryption	
I/O ports	Serial, USB, TCP/IP, IBSS/NTRIP, Bluetooth		
Data storage	6 GB internal memory		
	CMR+, CMRx, RTCM 2.1, RTCM 2.3, RTCM 3.0, RTCM 3.1, RTCM 3.2 input and output		
Data format			
Data format	24 NMEA outputs, GSOF, RT17 and RT27 outputs, 1 F	PPS output	
WEBUI		PPS output	
		•	
WEBUI	24 NMEA outputs, GSOF, RT17 and RT27 outputs, 1 F Offers simple configuration, operation, status, and da Accessible via Wi-Fi, Serial, USB, and Bluetooth	·	
	24 NMEA outputs, GSOF, RT17 and RT27 outputs, 1 F Offers simple configuration, operation, status, and da Accessible via Wi-Fi, Serial, USB, and Bluetooth D SOFTWARE	ata transfer	
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WEBUI SUPPORTED CONTROLLERS & FIEL	24 NMEA outputs, GSOF, RT17 and RT27 outputs, 1 F Offers simple configuration, operation, status, and da Accessible via Wi-Fi, Serial, USB, and Bluetooth D SOFTWARE	ata transfer	
WEBUI	24 NMEA outputs, GSOF, RT17 and RT27 outputs, 1 F Offers simple configuration, operation, status, and data Accessible via Wi-Fi, Serial, USB, and Bluetooth D SOFTWARE Trimble TSC7, Trimble T10, Trimble T7, Android and iC Trimble Access 2020.10 or later	ata transfer	
WEBUI SUPPORTED CONTROLLERS & FIEL AUGMENTED REALITY	24 NMEA outputs, GSOF, RT17 and RT27 outputs, 1 F Offers simple configuration, operation, status, and data Accessible via Wi-Fi, Serial, USB, and Bluetooth D SOFTWARE Trimble TSC7, Trimble T10, Trimble T7, Android and iC Trimble Access 2020.10 or later	ata transfer OS devices running supported apps	
WEBUI SUPPORTED CONTROLLERS & FIEL	24 NMEA outputs, GSOF, RT17 and RT27 outputs, 1 F Offers simple configuration, operation, status, and data Accessible via Wi-Fi, Serial, USB, and Bluetooth D SOFTWARE Trimble TSC7, Trimble T10, Trimble T7, Android and iC Trimble Access 2020.10 or later	ata transfer OS devices running supported apps Dugh Trimble SiteVision running on the Trimble TSC7 controller	



Trimble R12i GNSS SYSTEM







- 1 Challenging GNSS environments are locations where the receiver has sufficient satellite availability to achieve
- Challenging GNSS environments are locations where the receiver has sufficient satellite availability to achieve minimum accuracy requirements, but where the signal may be partly obstructed by and/or reflected off of frees, buildings, and other objects. Actual results may vary based on user's geographic location and atmospheric activity, scintillation levels, GNSS constellation health and availability, and level of multipath and signal occlusion. The current capability in the receivers is based on publicly available information. As such, Trimble cannot guarantee that these receivers will be fully compatible with a future generation of Galileo satellites or signals. Precision and reliability may be subject to anomalies due to multipath, obstructions, satellitie geometry, and atmospheric conditions. The specifications stated recommend the use of stable mounts in an open sky view, EMI and multipath clean environment, optimal GNSS constellation configurations, along with the use of survey practices that are generally accepted for performing the highest-order surveys for the applicable application including occupation times appropriate for baseline length. Baselines longer than 30 km require precise ephemeris and occupations up to 24 hours may be required to achieve the high precision static specification.

 Network RTK PPM values are referenced to the closest physical base station.

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 The references the overall positioning error estimate at the tip of the surveying pole throughout the tilt compensation range. RTK refers to the estimated horizontal precision of the underlying GNSS position, which is dependent on factors that affect GNSS solution quality. The 5 mm constant error component accounts for residual misalignment between the vertical axes of the receiver and the built-in lnertial Measurement Unit (IMU) after factory calibration, assuming the receiver is mounte

- assuming the receiver is mounted on a standard 2 m carbon fiber range pole which is properly calibrated and free from physical defects. The tilt-dependent error component is a function of the quality of the computed tilt azimuth, which is assumed here to be aligned using optimal GNSS conditions.

 RMS performance based on repeatable in field measurements. Achievable accuracy and initialization time may
- vary based on type and capability of receiver and antenna, user's geographic location and atmospheric activity, scintillation levels, GNSS constellation health and availability and level of multipath including obstructions such as large trees and buildings.
- Accuracies are dependent on GNSS satellite availability. xFill positioning without an xFill Premium subscription ends after 5 minutes of radio downtime. xFill Premium will continue beyond 5 minutes providing the solution has converged, with typical precisions not exceeding 3 cm horizontal, 7 cm vertical. xFill is not available in all regions, check with your local sales representative for more information.
- 9 RTK refers to the last reported precision before the correction source was lost and xFill started. 10 Depends on SBAS system performance.
 11 Receiver will operate normally to ~40 °C, internal batteries are rated to ~20 °C.
 12 Tracking GPS, GLONASS and SBAS satellites.

- 12 Hacking GF3, GLONAS3 and SARS statements.

 33 Varies with temperature and wireless data rate. When using a receiver and internal radio in the transmit mode, it is recommended that an external 6 Ah or higher battery is used.

 14 Varies with terrain and operating conditions.

 15 Due to local regulations, the integrated cellular modem cannot be enabled in China, Taiwan, or Brazil. A Trimble
- controller integrated cellular modem or external cellular modem can be used to obtain GNSS corrections via an IP (Internet Protocol) connection.
- 16 Bluetooth type approvals are country specific

Specifications subject to change without notice.



Made for **≰**iPhone | iPad









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